



Cas d'utilisation

UC1 Echanger avec un environnement virtuel

UC2 Télérobotique

Cahier des charges

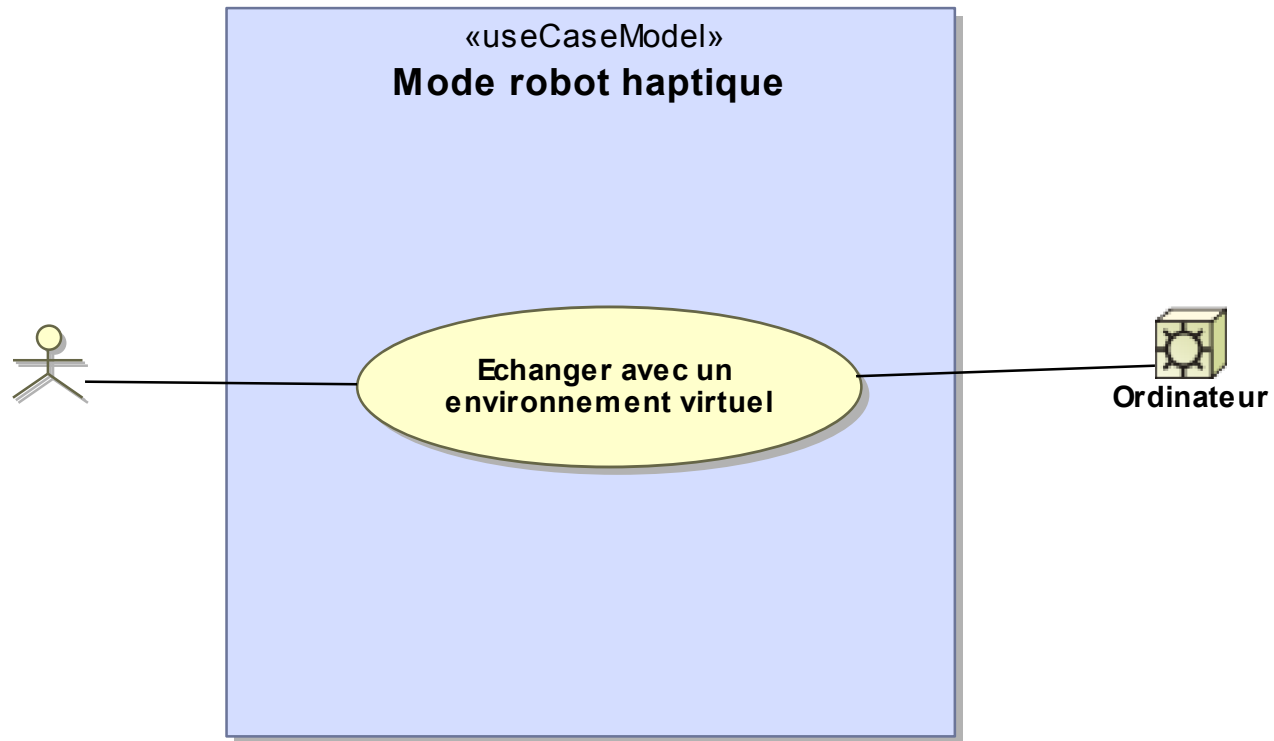
Exigences du système

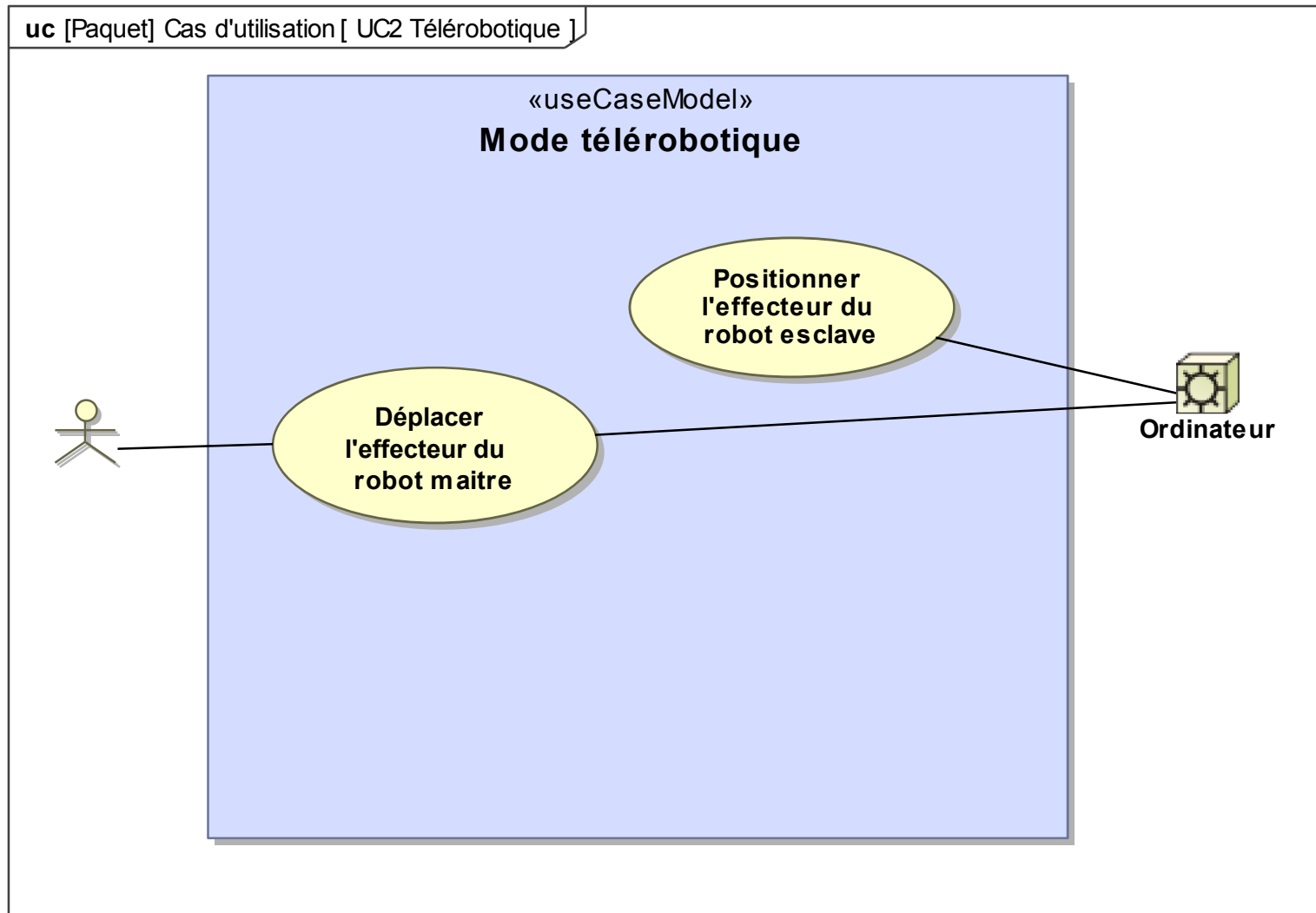
Description structurelle

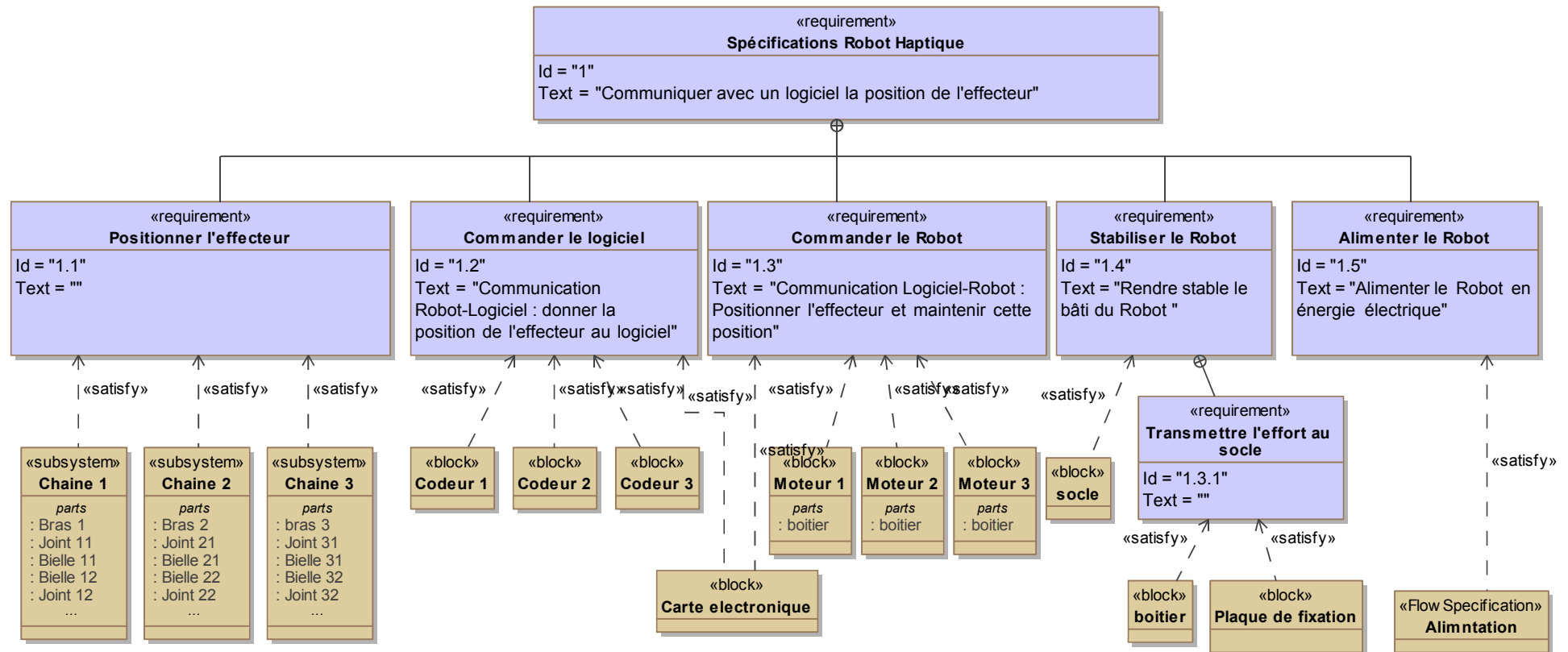
Définition des blocs

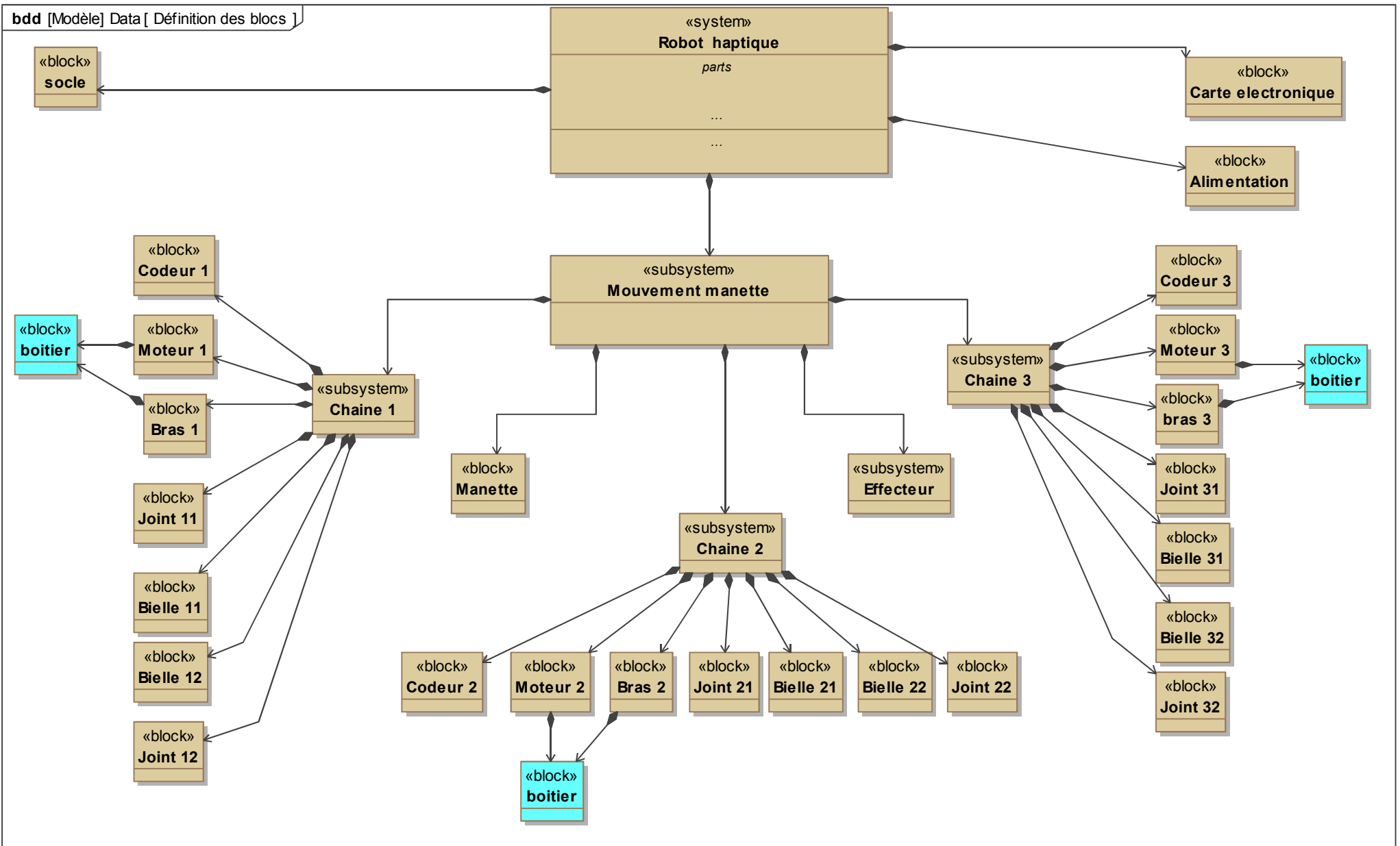
Blocs internes

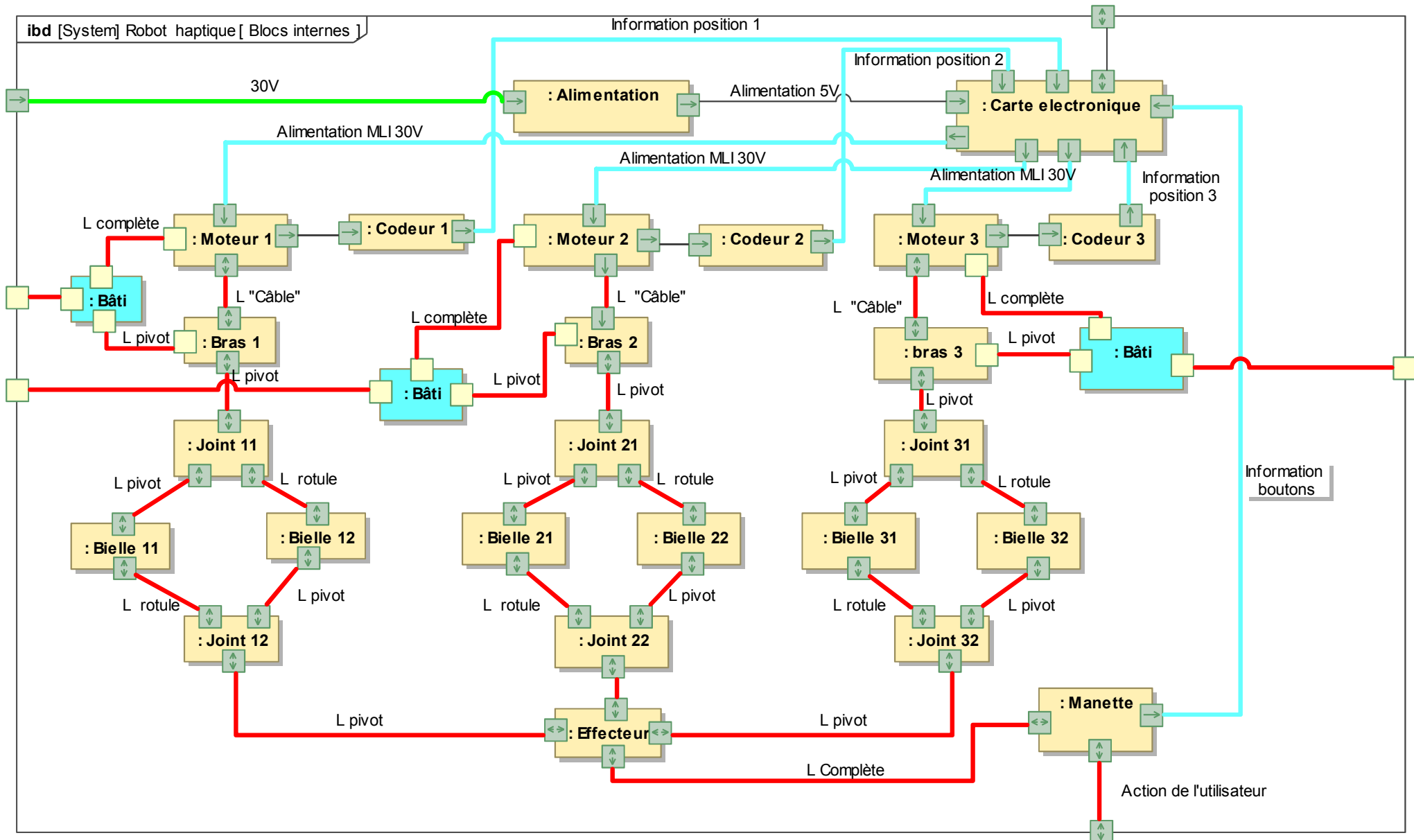
Schéma synoptique











Robot haptique schéma synoptique

